Process Synchronization (Part II)

Amir H. Payberah amir@sics.se

Amirkabir University of Technology (Tehran Polytechnic)

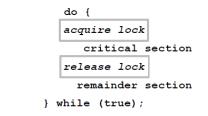


Motivation

Process Synchronization

- Maintaining consistency of shared data
- Critical-Section (CS) problem
- CS solutions:
 - · Peterson's solution
 - Synchronization Hardware
 - Mutex lock

Mutex Lock



```
acquire() {
  while (!available); /* busy wait */
  available = false;
}
release() {
  available = true;
}
```

Semaphores

 Synchronization tool that provides more sophisticated ways (than Mutex locks) for process to synchronize their activities.

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- Semaphore S: integer variable.
- Accessed via two atomic operations: wait() and signal()

wait() and signal()

```
wait(S) {
   while (S <= 0); // busy wait
    S--;
}
signal(S) {
    S++;
}</pre>
```

Counting and Binary Semaphore

 Counting semaphore: integer value can range over an unrestricted domain.

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- Counting semaphore: integer value can range over an unrestricted domain.
- ▶ Binary semaphore: integer value can range only between 0 and 1.
 - Same as a mutex lock.

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 - Initialize the semaphore to the number of available resources.
 - Call wait() before using a resource.
 - Call signal() after releasing a resource.
 - If S = 0: all resources are used, and processes that wish to use a resource will block until the count becomes greater than 0.

• Consider P_1 and P_2 that require C1 to happen before C2.

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• Create a semaphore S initialized to 0.

// Process P1
C1;
signal(S);
// Process P2
wait(S);
C2;

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• Create a semaphore S initialized to 0.

// Process P1
C1;
signal(S);
// Process P2
wait(S);
C2;

► The implementation still suffers from busy waiting.

Semaphore Implementation with no Busy Waiting (1/2)

► With each semaphore there is an associated waiting queue.

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- Each entry in a waiting queue has two data items:
 - Value (of type integer).
 - Pointer to next record in the list.

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- Each entry in a waiting queue has two data items:
 - Value (of type integer).
 - Pointer to next record in the list.

```
typedef struct {
    int value;
    struct process *list;
} semaphore;
```

Semaphore Implementation with no Busy Waiting (2/2)

- block: place the process invoking the operation on the appropriate waiting queue.
- wakeup: remove one of processes in the waiting queue and place it in the ready queue.

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```
wait(semaphore *S) {
   S->value--;
   if (S->value < 0) {
     // add this process to S->list;
     block();
   }
}
```

Semaphore Implementation with no Busy Waiting (2/2)

- block: place the process invoking the operation on the appropriate waiting queue.
- wakeup: remove one of processes in the waiting queue and place it in the ready queue.

```
wait(semaphore *S) {
   S->value--;
   if (S->value < 0) {
     // add this process to S->list;
     block();
   }
}
```

```
signal(semaphore *S) {
   S->value++;
   if (S->value <= 0) {
      // remove a process P from S->list;
      wakeup(P);
   }
}
```

Deadlock: two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes.

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- ▶ Let S and Q be two semaphores initialized to 1.

P_0	P ₁
<pre>wait(S);</pre>	<pre>wait(Q);</pre>
<pre>wait(Q);</pre>	<pre>wait(S);</pre>
<pre>signal(S);</pre>	<pre>signal(Q);</pre>
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Starvation

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- A process may never be removed from the semaphore queue in which it is suspended.
- If we remove processes from the list associated with a semaphore in LIFO (last-in, first-out) order.

Priority inversion: scheduling problem when lower-priority process holds a lock needed by higher-priority process.

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- Example:
 - *L* < *M* < *H*, assume process *H* requires *R*, which is accessed by process *L*.

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- *L* < *M* < *H*, assume process *H* requires *R*, which is accessed by process *L*.
- Now suppose that process *M* becomes runnable, thereby preempting process *L*.

Priority inversion: scheduling problem when lower-priority process holds a lock needed by higher-priority process.

• Example:

- *L* < *M* < *H*, assume process *H* requires *R*, which is accessed by process *L*.
- Now suppose that process *M* becomes runnable, thereby preempting process *L*.
- So, *M* has affected how long process *H* must wait.

Priority Inversion (2/2)

Solved via priority-inheritance protocol.

Priority Inversion (2/2)

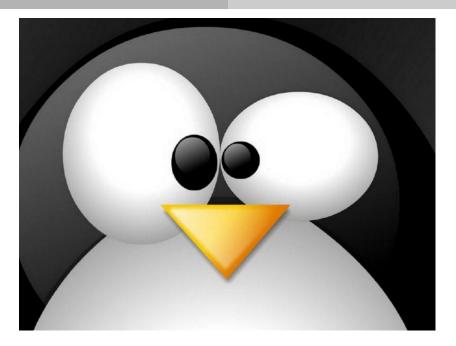
- Solved via priority-inheritance protocol.
 - All processes that are accessing resources needed by a higher-priority process inherit the higher priority until they are finished with the resources in question.

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 - All processes that are accessing resources needed by a higher-priority process inherit the higher priority until they are finished with the resources in question.
 - When they are finished, their priorities revert to their original values.

Priority Inversion (2/2)

- Solved via priority-inheritance protocol.
 - All processes that are accessing resources needed by a higher-priority process inherit the higher priority until they are finished with the resources in question.
 - When they are finished, their priorities revert to their original values.
- Process L temporarily inherits the priority of process H, thereby preventing process M from preempting its execution.



Opening an Unnamed Semaphore

sem_init() initializes a semaphore to the value specified by value.

#include <semaphore.h>
int sem_init(sem_t *sem, int pshared, unsigned int value);

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```

- pshared: whether the semaphore is shared between threads or processes.
 - == 0: shared between the threads, and sem is the address of either a variable.
 - > 0: shared between processes, and sem is the address of a shared memory.

Destroying an Unnamed Semaphore

sem_destroy() destroys the semaphore.

#include <semaphore.h>

int sem_destroy(sem_t *sem);

sem_wait() decrements the value of the semaphore.

```
#include <semaphore.h>
```

int sem_wait(sem_t *sem);

- value > 0: returns immediately.
- value == 0: blocks until the semaphore value rises above 0, then it decrements and sem_wait() returns.

sem_post() increments the value of the semaphore.

```
#include <semaphore.h>
```

int sem_post(sem_t *sem);

If the semaphore value was 0 before the sem_post(), and some other process is blocked waiting to decrement the semaphore, then that process is awoken.

Retrieving the Current Value of a Semaphore

sem_getvalue() returns the current value of the semaphore.

#include <semaphore.h>

int sem_getvalue(sem_t *sem, int *sval);

Producer-Consumer Example

Init the buffer and semaphore.

```
typedef struct {
    char buf[BSIZE];
    int nextin:
    int nextout;
    sem_t occupied;
    sem_t empty;
    sem_t mutex;
} buffer t:
buffer_t buffer;
sem_init(&buffer.mutex, 0, 1);
sem_init(&buffer.occupied, 0, 0);
sem_init(&buffer.empty,0, BSIZE);
buffer.nextin = buffer.nextout = 0;
```

Producer-Consumer Example

Producer

```
void producer(buffer_t *b, char item) {
    sem_wait(&b->empty);
    sem_wait(&b->mutex);
    b->buf[b->nextin] = item;
    b->nextin++;
    b->nextin %= BSIZE;
    sem_post(&b->mutex);
    sem_post(&b->occupied);
}
```

}

Producer-Consumer Example

Consumer

```
char consumer(buffer_t *b) {
    char item;
    sem_wait(&b->occupied);
    sem_wait(&b->mutex);
    item = b->buf[b->nextout];
    b->nextout++;
    b->nextout %= BSIZE;
    sem_post(&b->mutex);
    sem_post(&b->mutex);
    return(item);
}
```

- Incorrect use of semaphore operations:
 - signal(mutex) ... wait(mutex)

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- Omitting of wait(mutex) or signal(mutex) (or both)

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- wait(mutex) ... wait(mutex)
- Omitting of wait(mutex) or signal(mutex) (or both)
- Deadlock and starvation are possible.

► A high-level abstraction for process synchronization.

monitor monitor_name {

```
/* shared variable declarations */
function P1(...) { ... }
function P2(...) { ... }
function Pn(...) { ... }
initialization code(...) { ... }
```

- ► A high-level abstraction for process synchronization.
- Abstract data type, internal variables only accessible by code within the procedure.

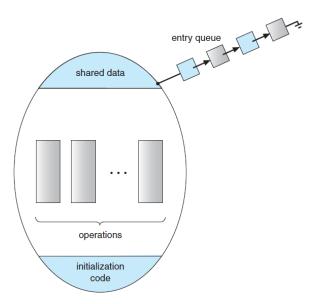
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- ► A high-level abstraction for process synchronization.
- Abstract data type, internal variables only accessible by code within the procedure.
- Only one process may be active within the monitor at a time.

```
monitor monitor_name {
   /* shared variable declarations */
   function P1(...) { ... }
   function P2(...) { ... }
   function Pn(...) { ... }
   initialization code(...) { ... }
}
```

A Monitor



Condition Variables

condition x, y;

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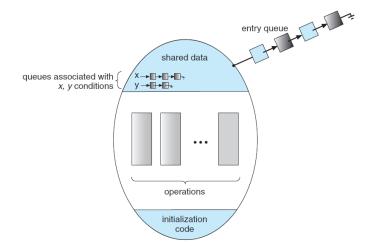
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- Two operations are allowed on a condition variable:
 - x.wait(): a process that invokes the operation is suspended until x.signal().
 - x.signal(): resumes one of processes (if any) that invoked
 x.wait().
 - If no x.wait() on the variable, then it has no effect on the variable.

A Monitor with Condition Variables



If process P invokes x.signal(), and process Q is suspended in x.wait(), what should happen next?

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- Options include:
 - Signal and wait: P waits until Q either leaves the monitor or it waits for another condition.

- If process P invokes x.signal(), and process Q is suspended in x.wait(), what should happen next?
 - Both Q and P cannot execute in parallel. If Q is resumed, then P must wait.
- Options include:
 - Signal and wait: P waits until Q either leaves the monitor or it waits for another condition.
 - Signal and continue: Q waits until P either leaves the monitor or it waits for another condition.

Resuming Processes within a Monitor

If several processes queued on condition x, and x.signal() executed, which should be resumed?

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Resuming Processes within a Monitor

- If several processes queued on condition x, and x.signal() executed, which should be resumed?
- ► FCFS (First-Come, First-Served) frequently not adequate.
- Conditional-wait construct of the form x.wait(c):
 - Where c is priority number.
 - Process with lowest number (highest priority) is scheduled next.

Single Resource Allocation

 Allocate a single resource among competing processes using priority numbers that specify the maximum time a process plans to use the resource.

```
R.acquire(t);
...
access the resource;
...
R.release();
```

▶ Where **R** is an instance of type **ResourceAllocator** monitor.

A Monitor to Allocate Single Resource

```
monitor ResourceAllocator {
  boolean busy;
  condition x;
  void acquire(int time) {
    if (busy)
      x.wait(time);
    busy = true;
  }
  void release() {
    busy = false;
    x.signal();
  }
  initialization code() {
    busy = false;
```

Classical Problems of Synchronization

Classical Problems of Synchronization

- Bounded-Buffer Problem
- Readers and Writers Problem
- Dining-Philosophers Problem

Bounded-Buffer Problem

Bounded-Buffer Problem (1/3)

- **n** buffers, each can hold one item.
- Semaphore mutex initialized to the value 1.
- Semaphore full initialized to the value 0.
- Semaphore empty initialized to the value n.

Bounded-Buffer Problem (2/3)

The structure of the producer process

```
do {
    ...
    /* produce an item in next produced */
    ...
    wait(empty);
    wait(mutex);
    ...
    /* add next produced to the buffer */
    ...
    signal(mutex);
    signal(full);
} while (true);
```

Bounded-Buffer Problem (3/3)

The structure of the consumer process

```
do {
   wait(full);
   wait(mutex);
   ...
   /* remove an item from buffer to next consumed */
   ...
   signal(mutex);
   signal(empty);
   ...
   /* consume the item in next consumed */
   ...
} while (true);
```

Readers and Writers Problem

Readers and Writers Problem (1/3)

► A shared data set among a number of concurrent processes:

- Readers: only read the data set; they do not perform any updates.
- Writers: can both read and write.

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- Problem: allow multiple readers to read at the same time, only one single writer can access the shared data at the same time.

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► A shared data set among a number of concurrent processes:

- Readers: only read the data set; they do not perform any updates.
- Writers: can both read and write.

Problem: allow multiple readers to read at the same time, only one single writer can access the shared data at the same time.

Shared Data

- Semaphore **rw_mutex** initialized to 1.
- Semaphore **mutex** initialized to 1.
- Integer read_count initialized to 0.

Readers and Writers Problem (2/3)

► The writer process.

```
do {
   wait(rw_mutex);
   ...
   /* writing is performed */
   ...
   signal(rw_mutex);
} while (true);
```

Readers and Writers Problem (3/3)

The reader process.

```
do {
  wait(mutex);
  read_count++;
  if (read_count == 1)
    wait(rw_mutex);
  signal(mutex);
  /* reading is performed */
  wait(mutex);
  read_count--;
  if (read count == 0)
    signal(rw_mutex);
  signal(mutex);
} while (true);
```

Dining-Philosophers Problem

- Philosophers spend their lives alternating thinking and eating.
- Don't interact with their neighbors, occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl.
- ▶ Need both to eat, then release both when done.

- Philosophers spend their lives alternating thinking and eating.
- Don't interact with their neighbors, occasionally try to pick up 2 chopsticks (one at a time) to eat from bowl.
- ▶ Need both to eat, then release both when done.
- ▶ In the case of 5 philosophers:
 - Shared data: bowl of rice (data set)
 - Shared data: semaphore chopstick[5] initialized to 1



The structure of philosopher i:

semaphore chopstick[5];

```
do {
   wait(chopstick[i]);
   wait(chopstick[(i+1) % 5]);
   ...
   /* eat for awhile */
   ...
   signal(chopstick[i]);
   signal(chopstick[(i+1) % 5]);
   ...
   /* think for awhile */
   ...
} while (true);
```

What is the problem with this algorithm?

Deadlock handling

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• At most 4 philosophers to sit simultaneously.

Deadlock handling

- At most 4 philosophers to sit simultaneously.
- Allow a philosopher to pick up the forks only if both are available.

Deadlock handling

- At most 4 philosophers to sit simultaneously.
- Allow a philosopher to pick up the forks only if both are available.
- Use an asymmetric solution: an odd-numbered philosopher picks up first the left chopstick and then the right chopstick. Even-numbered philosopher picks up first the right chopstick and then the left chopstick.

Dining-Philosophers with Monitor (1/3)

```
monitor DiningPhilosophers {
  enum {THINKING; HUNGRY, EATING} state[5];
  condition self[5];
  initialization code() {
   for (int i = 0; i < 5; i++)</pre>
    state[i] = THINKING;
  }
  void test(int i) {
    if ((state[i] == HUNGRY) &&
      (state[(i + 4) % 5] != EATING) &&
      (state[(i + 1) % 5] != EATING)) {
      state[i] = EATING :
      self[i].signal() ;
```

Dining-Philosophers with Monitor (2/3)

```
void pickup(int i) {
  state[i] = HUNGRY;
  test(i);
  if (state[i] != EATING) self[i].wait;
}
void putdown(int i) {
  state[i] = THINKING;
  // test left and right neighbors
  test((i + 4) % 5);
  test((i + 1) % 5);
}
```

Dining-Philosophers with Monitor (3/3)

Each philosopher i invokes the operations pickup() and putdown() in the following sequence:

```
DiningPhilosophers.pickup(i);
EAT
DiningPhilosophers.putdown(i);
```

► No deadlock, but starvation is possible.



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- Priority inversion
- Monitor: a high-level abstraction
- Classical problems: bounded-buffer, reader/writer, dining philosopher

Questions?

Acknowledgements

Some slides were derived from Avi Silberschatz slides.