



Linux Device Driver

(Module Programming)

Amir Hossein Payberah

payberah@yahoo.com

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- Linux Source
- Kernel Configuration and Compile
- Module Programming

Linux source tree



- Architecture
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- Memory Management
- Networking

Architecture



- Linux supports several different architectures.
- The **arch** directory contains all the platform specific code necessary to implementation low-level system interface.
 - Arm
 - Alpha
 - Athlon
 - i386
 - MIPS
 - SPARC
 - ...

Drivers



- This interaction and controlling of hardware is a small piece of the kernel called **drivers**.

- cdrom
- scsi
- usb
- char
- block
- sound
- ...

Filesystem



- In order for the kernel to know how to interact with the filesystem, it must know the structure of it.
 - CramFS
 - DevFS
 - ext2
 - ext3
 - FAT
 - ...

Init



- Init is the initial process of the Linux kernel.
- All initialization of the kernel is handled in this area.
 - Defining all devices
 - Parsing parameters
 - ...
- It is the **main** process on any UNIX systems.

Interprocess control



- IPC is a method for the kernel to manage processes and allow them to communicate with each other.
 - Message queue
 - Shared memory
 - semaphore

Kernel



- It contains the code to provide the other areas of the kernel with ways to communicate.
- Several functions that are used through other subsystem of the kernel.
 - panic
 - printk
 - softirq
 - ...

Memory management



- It is responsible for keeping track of all system memory and its usage by the kernel.

Networking



- Linux supports several protocol suites in the kernel.
 - 802
 - Appletalk
 - ATM
 - BGP
 - Bluetooth
 - Ethernet
 - IPV4
 - ...

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Kernel configuration



- make oldconfig
- make menuconfig
- make xconfig

Kernel configuration



```
Linux Kernel v2.6.5-1.358custom Configuration

Linux Kernel Configuration
Arrow keys navigate the menu. <Enter> selects submenus --->. Highlighted letters are hotkeys. Pressing <Y>
includes, <N> excludes, <M> modularizes features. Press <Esc><Esc> to exit, <?> for Help. Legend: [*] built-in
[ ] excluded <M> module < > module capable

Code maturity level options --->
General setup --->
Loadable module support --->
Processor type and features --->
Power management options (ACPI, APM) --->
Bus options (PCI, PCMCIA, EISA, MCA, ISA) --->
Executable file formats --->
Device Drivers --->
File systems --->
Profiling support --->
Kernel hacking --->
Security options --->
Cryptographic options --->
Library routines --->
---
Load an Alternate Configuration File
Save Configuration to an Alternate File

<Select> < Exit > < Help >
```

Kernel compile



- Kernel 2.4.x and older
 - make menuconfig
 - make dep
 - make bzImage
 - make modules
 - make modules_install
 - make install

Kernel compile



- Kernel 2.6.x
 - make
 - make install
- Clean Kernel Source
 - make clean
 - make mrproper

Kernel version



- Kernel version can be broken down into four sections:
 - Major version
 - Minor version
 - Sublevel number
 - Extraversion level

Kernel version



- **Even** numbered minor version are **stable** kernels.
- **Odd** numbered version are **development** release

Stable release number

Version number

2.2.14

Even number denotes stable kernel

Development release number

Version number

2.3.51

Odd number denotes development kernel

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Module vs. Application



■ Application

- An application performs a single task from beginning to end.
- An application runs in **user space**.

■ Module

- A module registers itself in order to serve future requests.
- A module runs in **kernel space**.
- The role of a module is to **extend kernel functionality**.

Hello World



```
#define MODULE
#include <linux/module.h>
//-----
int init_module()
{
    printk("<1>Hello World ...\n");
    return 0;
}
//-----
void cleanup_module()
{
    printk("<1>Goodbye ...\n");
}
```

Compiling “Hello World”



```
root# gcc -c hello.c
```

```
root# insmod ./hello.o
```

```
Hello World ...
```

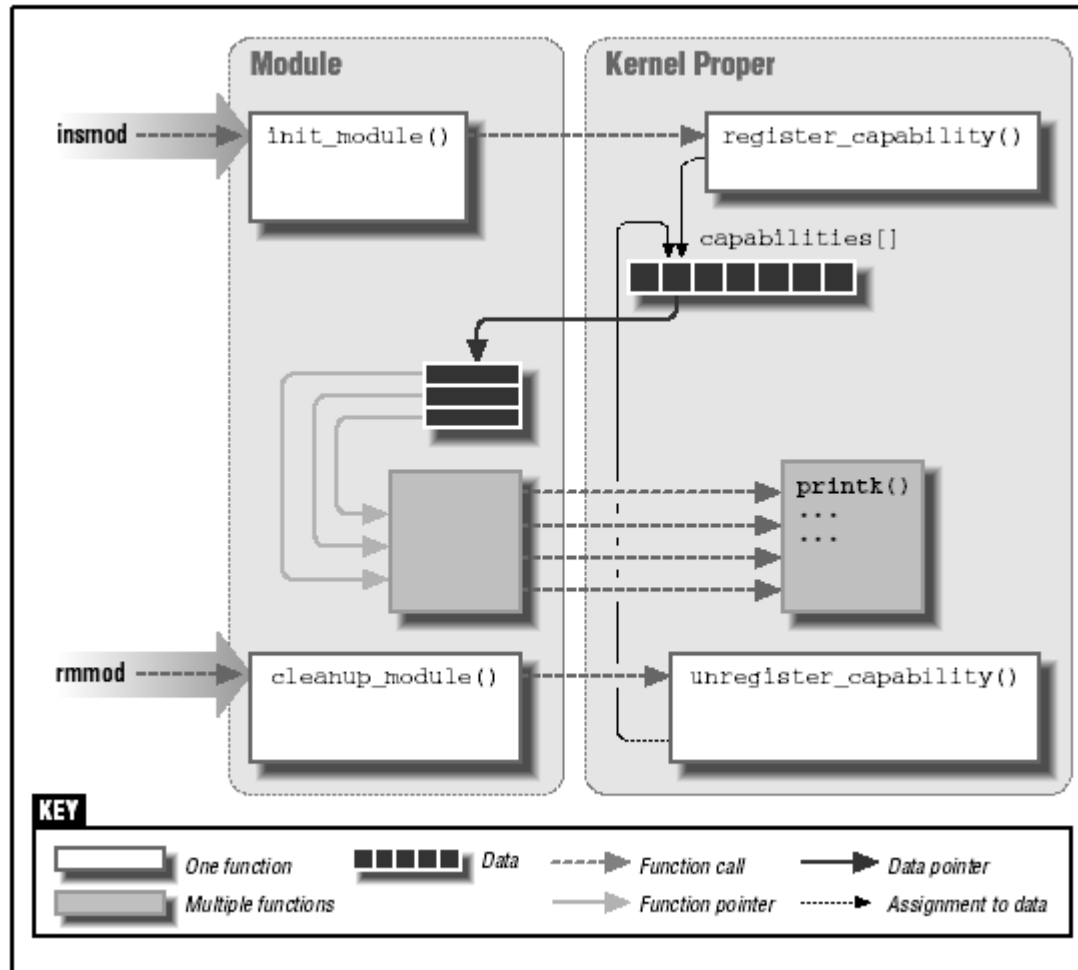
```
/var/log/messages
```

```
root# rmmmod hello
```

```
Goodbye ...
```

```
root#
```

Linking a module to the kernel



Module header files



- Because **no** library is linked to modules, source files should **never** include the usual header files.
 - `include/asm`
 - `include/linux`

Module compile notes



- `#define __KERNEL__`
 - Much of the kernel specific content in the kernel headers is unavailable without this symbol.
- `#define MODULE`
 - It must define before `#include <linux/module>`
- `-O`
 - gcc doesn't expand `inline` functions unless optimization is enabled.
- `-Wall`
 - In order to prevent unpleasant errors.

Makefile



```
KERNELDIR = /usr/src/include  
CFLAGS = -D__KERNEL__ -DMODULE  
-I$(KERNELDIR)/include  
-O -Wall
```

Version dependency



- Module's code has to be **recompiled** for each version of the kernel that it will be linked to.

Version dependency



- Each module defines a symbol called `__module-kernel-version`
 - Insmod matches it against the version number of current kernel.
 - The compiler will define this symbol whenever the module's code includes `<linux/module.h>`
 - This placed in the `.modinfo` ELF section.
 - ELF (Executable Linking and Format)

Version dependency



- When asked to load a module, insmod follows its own search path to look for the object file (`/lib/module`).
- In case of version mismatch
 - Force to install (`insmod -f`).
 - This operation is not safe.

Version macros



- UTS_RELEASE
 - Kernel version : 2.3.48
- LINUX_VERSION_CODE
 - Kernel binary version : 2.3.48 → 131888
- KERNEL_VERSION(major, minor, release)
 - $\text{KERNEL_VERSION}(2.3.48) = 131888$
- They are defined in `<linux/version.h>`

Kernel symbol table



- It contains the addresses of global kernel items (**functions and variables**).
 - They are needed to implement modularized drivers.
 - /proc/ksyms
- When a module is loaded, symbol exported by the module becomes part of the kernel symbol table.

Symbol table macros



- EXPORT_NO_SYMBOLS
- EXPORT_SYMBOL(name)
- EXPORT_SYMBOL_NOVERS(name)

Error handling



- If any errors occur when you register utilities, you must undo any registration before the failure.
- Error recovery is sometimes best handled with the **goto** statement.

Error handling



```
int init_module()
{
    int err;
    err = register_this(ptr1, "skull");
    if (err)
        goto fail_this;
    ...
    return 0;
fail_this: return err;
}
```

Usage count



- The system keeps **usage count** for every module in order to determine whether the module can be **safely** removed.
 - `/proc/modules`

Usage count macros



- **MOD_INC_USE_COUNT**
 - Increment the count.
- **MOD_DEC_USE_COUNT**
 - Decrements the count.
- **MOD_IN_USE**
 - Evaluate to true if the count is not zero

Module configuration



- Parameter values can be assigned at load time by insmod.
 - `insmod skull.o ival=666 sval="hello"`
- Supported types:
 - Integer : i
 - Long : l
 - String : s
 - Byte : b
 - Short (two bytes) : h

Module configuration



```
{ int num = 0;  
  MODULE_PARM (num, "i");  
  
{ char *str;  
  MODULE_PARM (str, "s");  
  
{ int array[4];  
  MODULE_PARM (array, "2-4i");
```

A large, faded, light gray cartoon penguin is centered in the background, appearing to be in a questioning or thinking pose with its hands near its face. A horizontal orange gradient bar with a pixelated end on the left side passes behind the penguin.

Question?